MIC7 Lecture 5

Ultra-Small Deep Space Mission Telecommunication Systems Design

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Biography

- Dr. Atsushi Tomiki received B.E., M.E., and Ph.D. degrees from Tokyo Denki University in 2002, 2004, and 2007, respectively. He joined the Japan Aerospace Exploration Agency (JAXA), Tokyo, Japan in 2007 and was engaged in development on deep space telecommunication systems.
- \Box He is currently an associate professor at the Department of Spacecraft Engineering, the Institute of Space and Astronautical Science in the Sagamihara Campus. His research interests include wireless telecommunication systems in low-cost planetary and lunar exploration, ultra wideband systems for fly-by-wireless spacecraft, and electromagnetic compatibility in scientific spacecrafts.

1. Introduction and Background

Plan of ISAS Deep Spacecraft Fleet

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1. Introduction and Background

Sample return mission in the outer region of the solar system adopted in the Master Plan 2017.

2. Overview of Deep Space Telecommunication System

(a) (b) (c)

Telecommunication System of (a) 64m antenna of Usuda Deep Space Center, (b) Hayabusa2 spacecraft, and (c) 54m antenna of Misasa for Ka-band reception, which is currently under construction.

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Deep Space Network Resources

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Command and Telemetry Modulation and Codling

Link Equation on Physical layer

Satellite frequency band

Common Frequencies for space exploration

- S band UPLINK 2.0, DOWNLINK 2.2 GHz on category-A region
- X band UPLINK 7.1, DOWNLINK 8.45 GHz on category-A and -B(Deep Space) region
- Ka band DOWNLINK 32 GHz

Satellite frequency band

- Frequency allocations are defined by international organizations such as ITU-R, SFCG, and CCSDS. Command commands (uplink) and telemetry (downlink) are divided into their own frequencies and also used by channel allocation.
- Each spacecraft is assigned a frequency after international coordination, including the presence or absence of interference to other communication systems, and a radio station license is granted by the regulatory authority of each country.
- In recent years, advances in semiconductor technology such as MMICs have led to the increased use of the X and Ka bands, which allow for wider bandwidths.

Typical Command and Telemetry Modulation and Coding

Typical telemetry channel encoding improve the Bit Error Rate

2. Overview of Deep Space Telecommunication System

Micro-satellite missions for deep space exploration: (a) PROCYON, a 50 kg-class micro-spacecraft, (b) OMOTENASHI, a 6U-Cubesat, and (c) **EQUULEUS**

Block Diagram of PROCYON Telecommunication Systems

Comparison of spacecraft frequency band and total-mass

Onboard Resources comparison Between Microsatellite and Small Satellite missions

Deep Space Transponder

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\blacktriangle Applicable Ultra-Small Spacecraft Antennas

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PROCYON Components specifications

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Command and Telemetry performance assuming PROCYON onboard telecommunication system

- Distance at which a Micro-satellite with a communication system equivalent to PROCYON can communicate with the Usuda 64m antenna
	- Downlink bit-rate 1.024 [kbps]
	- Uplink bit-rate 125 [bps]
- It is directed to the HGA and just barely reaches Mars. Because of asymmetric communication, there is much more room for uplink.

Command and Telemetry performance assuming PROCYON onboard telecommunication system

- Distance at which a Micro-satellite with a communication system equivalent to PROCYON can communicate with the Usuda 64m antenna
	- Downlink bit-rate 128 [bps]
	- Uplink bit-rate 125 [bps]
- The telemetry is just barely reachable from Jupiter even if the HGA is oriented. Direct communication with Jupiter is possible by improving the antenna, SSPA, and coding by about 10[dB], but relay communication with the mother ship is essential for high bit rate.

Conclusion 1

- As satellites become smaller, the power generated by SAPs becomes smaller, and the equivalent isotropic radiated power (EIRP), which radiates radio waves into space, decreases significantly. For nanosatellites to communicate in deep space, a decrease in EIRP means a decrease in communication data rate. In order to communicate with the earth at a practical communication speed, it is essential to improve the EIRP. In addition, free antenna directional control is required to ease the attitude constraint.
	- Reduction of instrumentation loss (using the waveguide possible)
	- Planar patch array antenna, or such as deployable high-gain antenna
	- Improvement of power efficiency by New Semiconductor Devices
	- ◼ Coding gain reduces the transmit power

Conclusion 2

 Since the resources of the bus section will be reduced, it is also essential to make the communication device smaller and lighter. Miniaturization cannot be achieved without the use of consumer components. Even with the use of recent high-performance semiconductors and ultra-small components, as typified by cell phones and smartphones, miniaturization has already reached its limit in terms of mounting. The size of 0.5 to 1.0 [U] is the limit, and to reduce the size below this, integration of communication devices and system-on-a-chip are essential.

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