

IDEA: In-situ Debris Environmental Awareness

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Background & Motivation

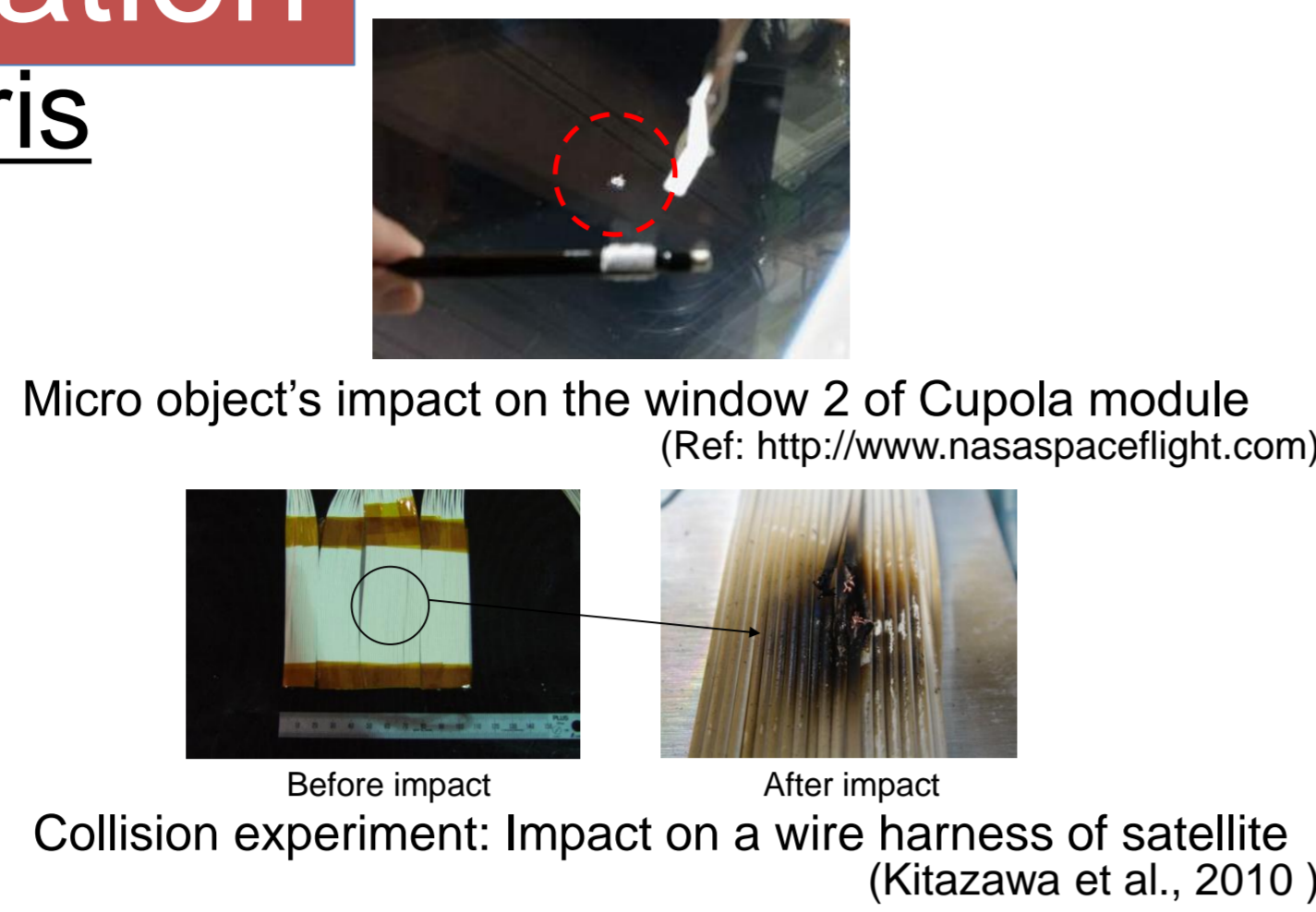
Dangerousness of Micro debris

Once micro debris collides with spacecraft, the impact would be a trigger of **critical damages** on spacecraft

- Radiator panels of STS (Endeavour and Atlantis)
- Window of the Cupola module of the International Space Station
- ADEOS-2
- ✓ Micro debris is assumed a factor causing a solar panel failure

Collisions of micro debris with spacecraft are recognized as **not special events** in space

➔ **Accurate comprehension of debris distribution is essential**



Debris Environment model

e.g.) MASTER (ESA), ORDEM (NASA)

Describe and characterize the current and future debris environment. However, those models still remain a lot of uncertainties in the micron-regime

➔ **Calibration with measurement data is fundamental**

Mission Objectives

Objectives of IDEA project

To construct the monitoring network by a group of micro satellites (IDEA satellites)

Data utilizations

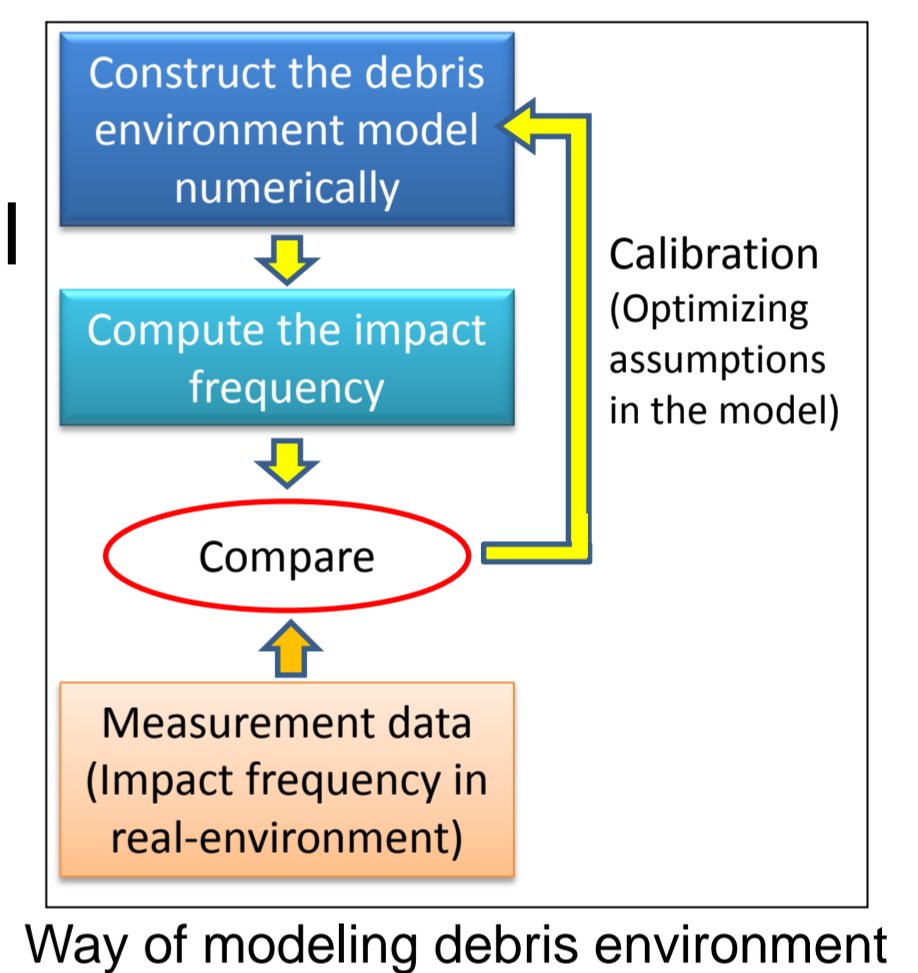
Collected data by IDEA-1 contributes following utilizations

1. To validate the existing debris environment models
 - With the Poisson distribution, the collision frequency is estimated by the measurement error of population
 - Even if measurement data is only few, those data are useful to define the population threshold in the environment

2. To develop the up-to-date debris environment model
 - Debris environment model is constructed numerically
 - The model is calibrated by comparing the impact frequency between our model and measurement data
 - Optimizing assumptions in our model is continued to approach the real debris environment

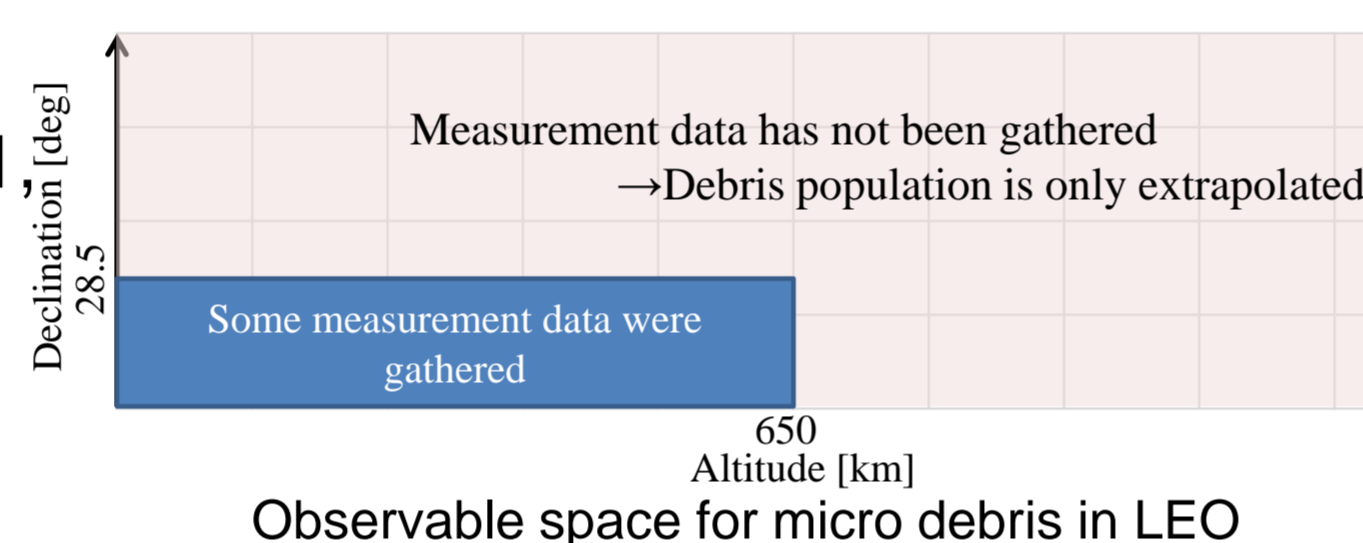
3. To detect breakup events
 - Analyzing the multi-points **cluster** information makes estimating several specifications of breakup events possible
 - ✓ Breakup events generate lots of micro debris, and most micro debris grows in a **cluster** during certain period
 - ✓ Cluster can be detected only when the specific time information of impacts are clear

- IDEA satellites can catch and transmit measurement data, so we can **immediately** recognize the fluctuation of debris environment caused by breakup events



Micro debris Observation

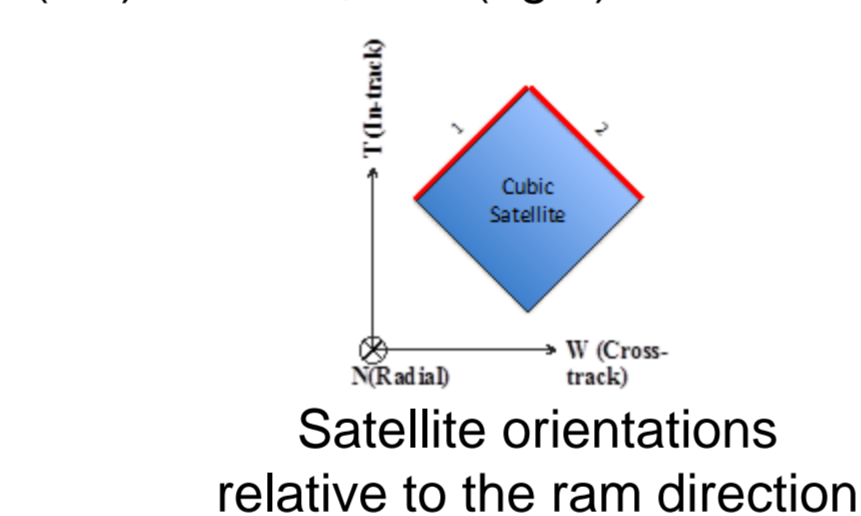
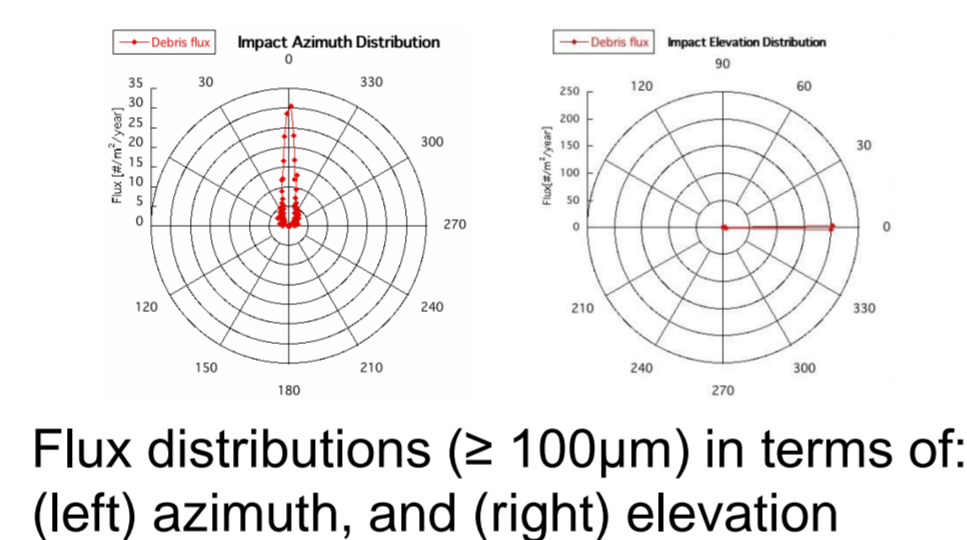
- **In-situ measurement** is necessary for observation of micro debris
 - ✓ 100µm-1mm objects cannot be detected from ground
- The existing observation method for micro debris
 - ➔ **Inspection of impact marks on surface on retrieval spacecraft only**
 - ✓ Reveals only a time-integrated debris population during the observation
 - ◆ That means the collected data cannot tell the time and position of each debris impacts
 - ✓ Because retrieval spacecraft is captured by space shuttles, the observable space is limited in only the area that shuttle can achieve
 - ◆ The measurement data in the area > 650 km altitude and outside the 28.5° declination has not existed
 - ✓ Since space shuttles were retired in 2011, monitoring systems do not exist
 - **The accumulated data is insufficient in overall space**



Development of IDEA-1

Orbit

- Sun-synchronous orbit, alt: 798 km
 - ✓ Debris flux is relatively high because of major breakup events:
 - the intentional destruction of the FY-1C in 2007
 - the collision of the Cosmos 2251 and the Iridium 33 in 2009
 - ✓ 65 hits (≥100µm) are estimated by MASTER-2009

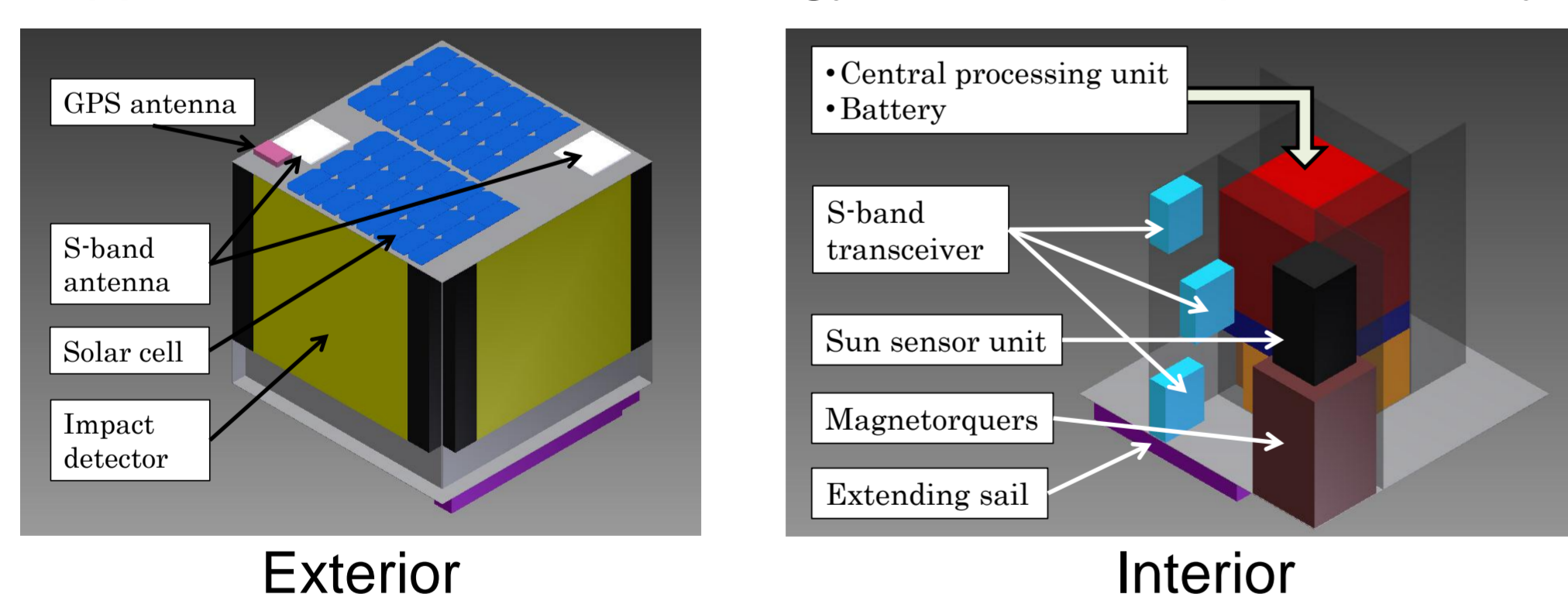


Requirement

- Installing two sheets of Dust impact detectors on neighboring side surfaces
- Keeping on exposing the detectors to the ram direction
 - ✓ According to an analysis by MASTER-2009, there is an intensive flux distribution along the ram direction in the planning orbit

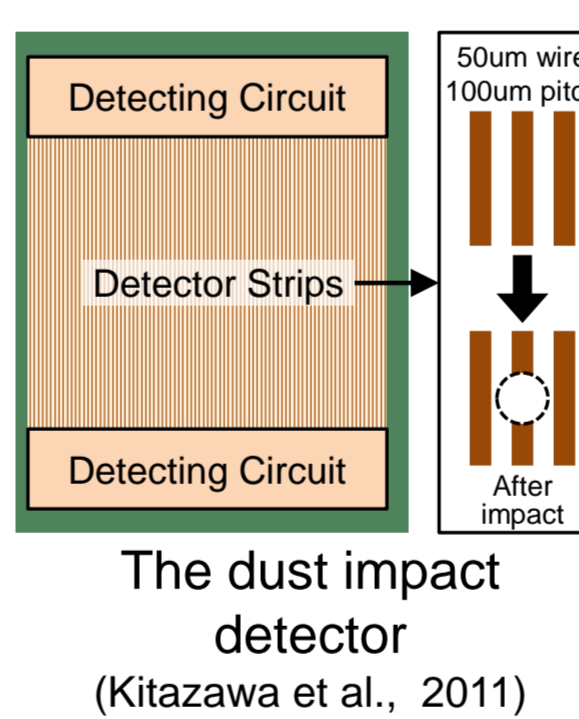
Concept

- Simple design focused on the micro debris detections
- Applied well-verified technology and devices preferentially



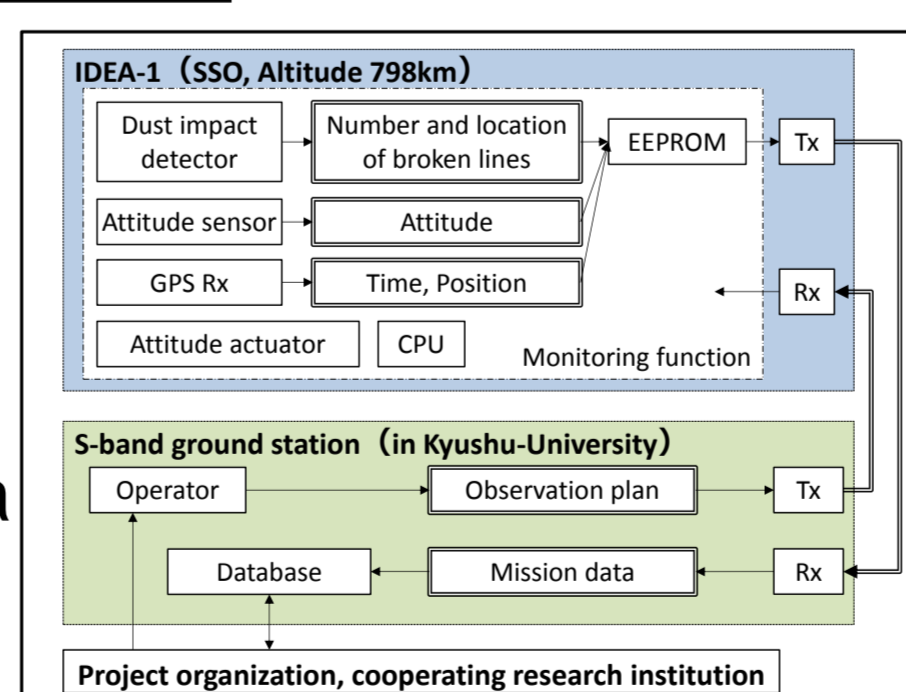
Dust impact detector (Mission instrument)

- Under developing at Japan Aerospace Exploration Agency (JAXA)
- Consisting of 350 conductive stripes being spaced on non-conductive thin film
- Detecting debris (≥100µm) impact and measuring its size within ±100 µm error
- 0.12 m² detective area



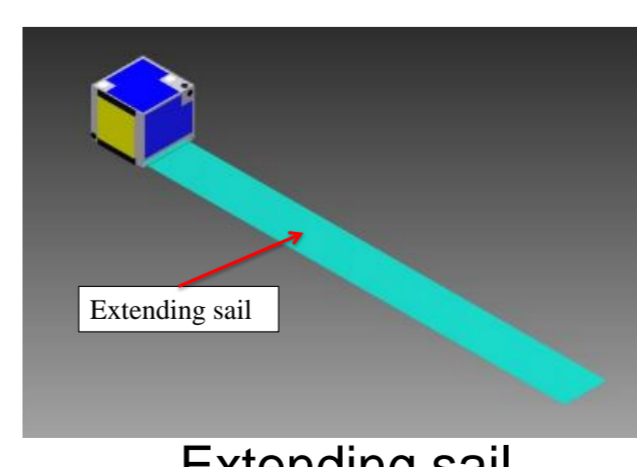
Concept of Operation

- Collecting mission data
 - ✓ Debris size, time, location of IDEA-1, attitude
- Accumulating data from IDEA-1 in database server
 - This database is released to our project members and researchers who cooperate with our project



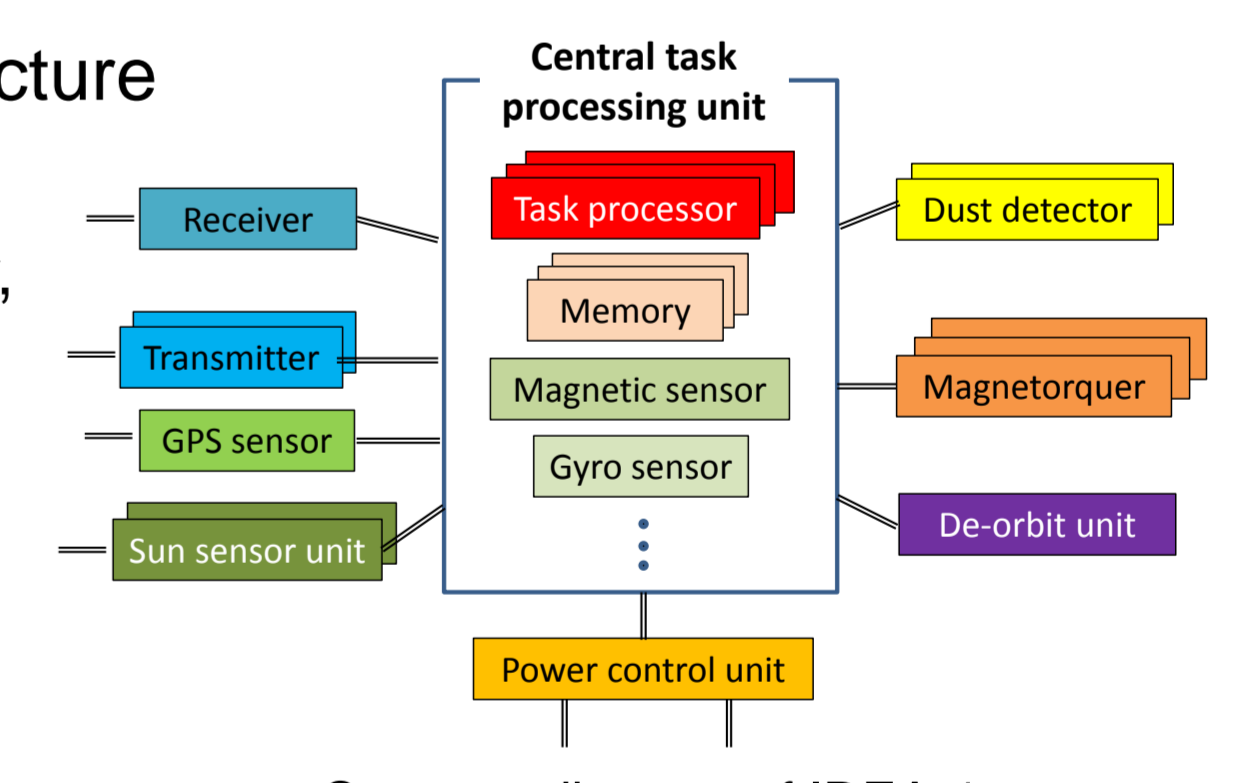
De-orbit

- Equipping an extending sail, in order to decay into atmosphere within 25 years after the end of operation.
- The sail enlarges own surface area at the end of mission to increase atmospheric drag
- Dimension: 0.35 m (width) × 4 m (length)

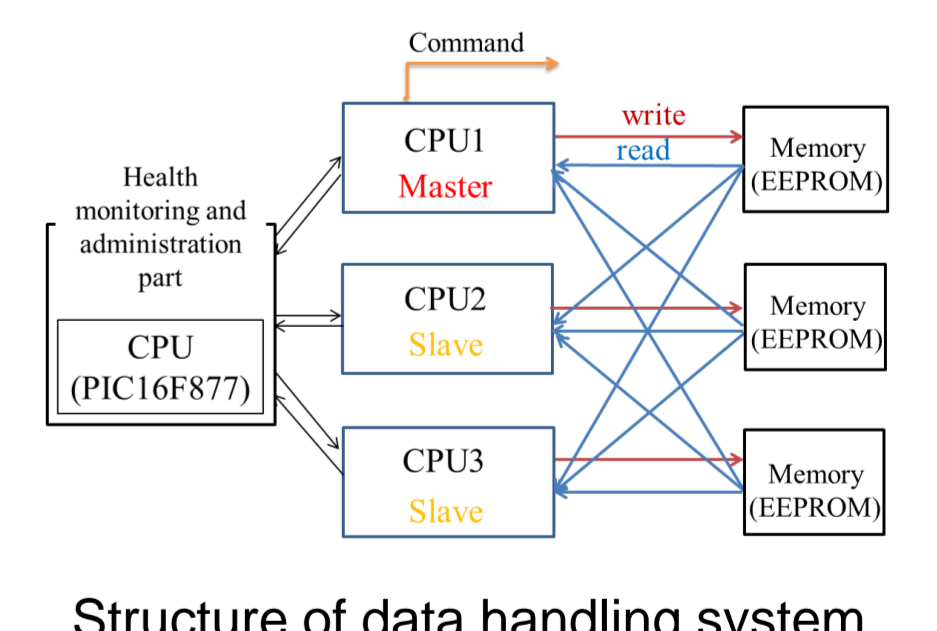


Command & Data Handling

- Integrated task process architecture
- Triple redundancy system
 - ✓ Transmitting mission data triply, and selects a data by majority voting
 - Tolerating one bit invert by Single Event Upset (SEU) on one CPU and at most two troubles of onboard CPUs for data processing
- Health monitoring and administration part
 - ✓ Monitoring a latch-up current in task processors
 - ✓ Transferring the authority of Master to other one Slave CPU, when some troubles occurred in Master CPU
 - ✓ Using PIC16F877, which has excellent durability for Single Event



Systems diagram of IDEA-1 (Integrated task process architecture)



Structure of data handling system

Implementation Plan

- Aiming to develop the other IDEA satellites every two years
- Developing a Bread Board Model (BBM) at present
- Going to accomplish FM of IDEA-1 on March, 2014

Year	2012			2013												2014		
Month	10	11	12	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3
IDEA-1																		
Design																		
Hardware																		
Software																		
Ground Station																		
Milestone																		
IDEA-2																		
Design																		

Top-level project schedule

Specifications of IDEA-1	
Size, Mass	50cm × 50cm × 50cm, 25 kg
Mission instrument	Dust impact detector Measuring size range: 100µm-1mm, Sensor area: 0.12 m ² /sheet × 2 sheets
Bus functions	
Command and data handling	Integrated task process architecture, Health monitoring and administration part EEPROM, GPS receiver
Attitude determination	Angular sensor: PSD sun sensor, Magnetometer Angular rate sensor: MEMS gyro
Attitude control	3-axis Magnetorquer
Power	GaAs solar cell, NiMH battery, 31.5 W (average generation), 35.8 W (peak consumption)
Communications	S-band transceiver, Patch antenna Receiver: PCM-PSK/PM, 50 W (transmission power), 2.10 GHz, 20kbps Transmitter: BPSK, 0.5 W (transmission power), 2.25 GHz, 30 kbps
De-orbit	Extending sail (35cm × 4m)
Structure and thermal control	Skin-Frame structure (A5052-H32), PAF239M separation mechanism, Passive thermal control